



Stäubli WFT GmbH

Place | Date | Name





Stäubli WFT GmbH / Sulzbach-Rosenberg

Approximately 85 employees work at this location in Sulzbach-Rosenberg specializing on mobility topics.



- 1998
 "Wittich Fertigungstechnik" was founded by Franz Wittich
- 2001 renamed to "WFT GmbH & Co. KG"
- 2008
 Development of the first AGV with the patented drive unit
- 2018
 WFT becomes part of STÄUBLI Group renamed to "STÄUBLI WFT GmbH"
- Today
 About 200 WFTM.I.T. (Modular Individual Transport system) installed in 9 different market segments





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Automotive

Aviation

Construction

Energy

Food

GI

Glass

Metal

Packaging

Plastics











We are covering your mobility demands modular by



- Size
- Motion type
- Operating mode
- Drive unit
- Energy
- **Options**

Wide range of payload possibilities with a single M.I.T.



500 kg

Payload



500.000 kg









We are covering your mobility demands modular by

Payload



Size

- Motion type
- Operating mode
- Drive unit
- Energy
- **Options**

Wide range of size availabilities with a **single** M.I.T.



1 m x 1.7 m

Dimension (X/Y)

Height down to 200 mm (depending the payload needed)



3.5 m x 15 m or even more









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- Payload
- Size



- Operating mode
- Drive unit
- Energy
- **Options**





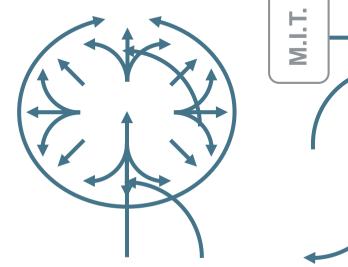
Differential motion





Two different M.I.T. motion types available

Omnidirectional motion











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- Payload
- Size
- Motion type

Operating mode

- Drive unit
- Energy
- Options



Manual mode









We are covering your mobility demands modular by

- Payload
- Size
- Motion type

Operating mode

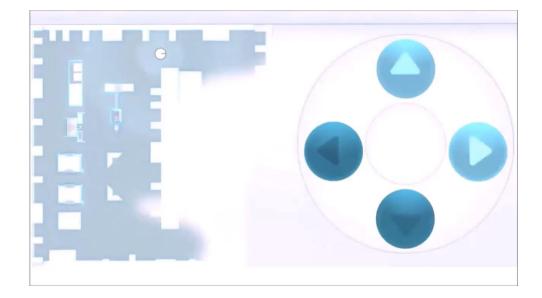
- Drive unit
- Energy
- Options



Manual mode



Autonomous mode







We are covering your mobility demands modular by

- Payload
- Size
- Motion type

Operating mode

- Drive unit
- Energy
- Options



Manual mode



Semiautonomous mode

Benefit from combining

both modes

Manual where needed Autonomous where feasible Autonomous mode

- Mapping
- Definition of routes
- Autonomous tasks
 - guidance
 - GPS
 - optical
 - transponder
 - SLAM navigation



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- Payload
- Size
- Motion type

Operating mode

- Drive unit
- Energy
- Options



Manual mode



Semiautonomous mode

Benefit from combining both modes

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Autonomous mode

- Mapping
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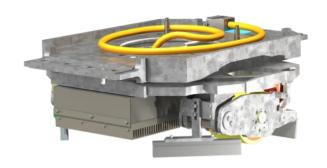


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- Payload
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- Operating mode

Drive unit

- Energy
- Options



Patented, modular and efficient 48V drive unit

- Robust drive unit with suspension
- Ready for in- and outdoor usage
- Low wheel friction due to intelligent control technology
- Low-wear and easy to maintain
- High overall efficiency





We are covering your mobility demands modular by

Payload

Size

Motion type

Operating mode

Drive unit

Energy

Options

Different M.I.T. charging possibilities available

with contact

manual connection

automatic connection

contactless

inductive







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- Options



Different M.I.T. option possibilities available

Software option

coupling of M.I.T.







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- Operating mode
- Drive unit
- Energy





Software option

coupling of M.I.T.



Mechanical options

carrying device



conveyor



lifting unitmanipulator / robot



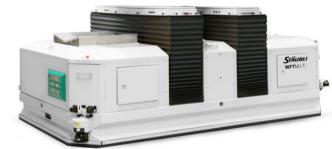






We are covering your mobility demands by

- **MODULARITY**
- **SCALABILITY**
- CONNECTIVITY
- INDIVIDUAL ADD-ONS
- HIGH RELIABILITY















"In reality, a test of an outdoor transport robot is currently taking place in the Leipzig plant, which independently transports truck trailers from the parking space to the unloading and loading station in the plant.

A mobile platform drives under the semi-trailer, couples it to the truck and manoeuvres it through the plant. Sensors and cameras record the entire environment - even behind the trailer."





Thank you for your attention!

